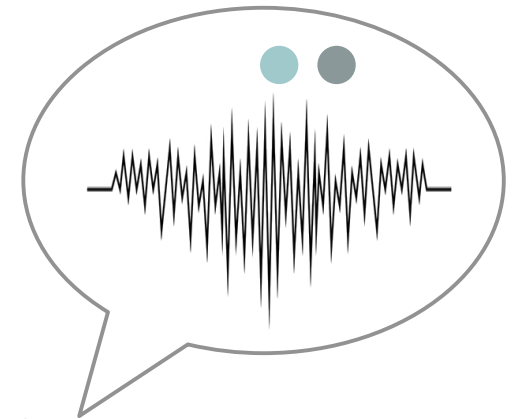
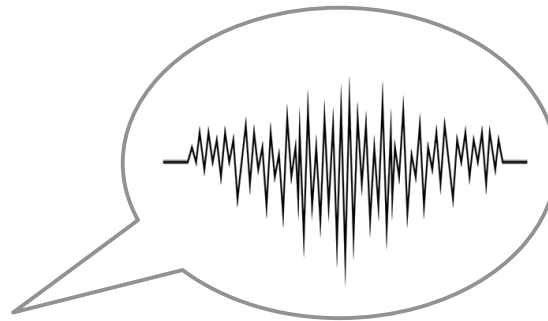


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## Modelado, control motor y percepción vocal



$$m\ddot{x} = -k(x) - b(x, \dot{x}) + P(x, \dot{x})$$

$$\frac{1}{S} \frac{\partial}{\partial x} \left( S \frac{\partial p}{\partial x} \right) - \frac{1}{c^2} \frac{\partial^2 p}{\partial t^2} = 0$$

Gabriel Mindlin

Marcos

Trevisan

Florenca

Assaneo



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I:	I	U	U:	Iə	eI		
leave	hit	put	too	fear	say		
e	ə	ɜ	ɔ:	ʊə	ɔI	əʊ	
bet	about	word	caught	pore	toy	no	
æ	ʌ	ɑ:	ɒ	eə	aI	aʊ	
hat	cut	part	dot	lair	pie	cow	
p	b	t	d	tʃ	dʒ	k	g
pit	bit	tea	day	church	jog	cat	get
f	v	θ	ð	s	z	ʃ	ʒ
few	yet	think	the	seven	zoo	shoe	beige
m	n	ŋ	h	l	r	w	j
men	new	bring	hi	let	red	west	yellow

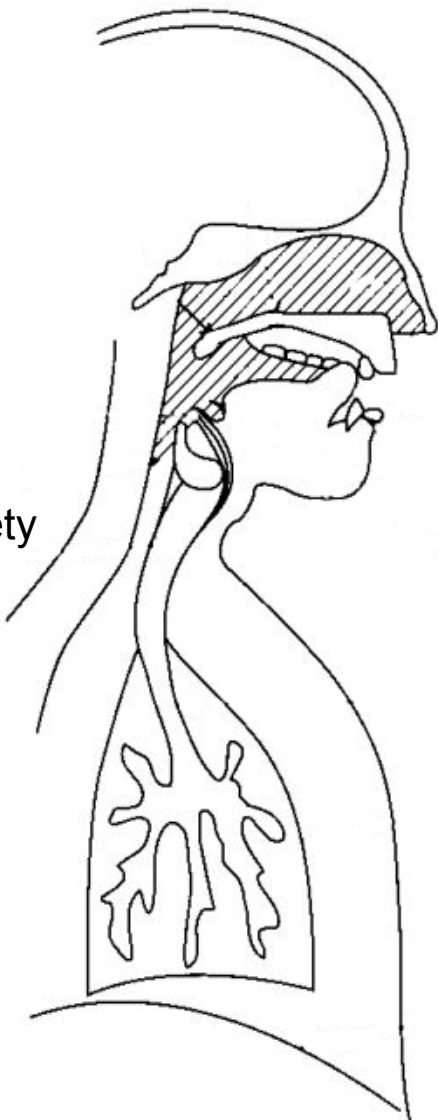
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Trevisan  
Florescia  
Assaneo



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## Modelado, control motor y percepción vocal

Science Gallery,  
Max Planck Society



I:	I	U	U:	Iə	eI		
leave	hit	put	too	fear	say		
e	ə	ɜ	ɔ:	ʊə	ɔI	əʊ	
bet	about	word	caught	pore	toy	no	
æ	ʌ	ɑ:	ɒ	eə	aI	aʊ	
hat	cut	part	dot	lair	pie	cow	
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m	n	ŋ	h	l	r	w	j
men	new	bring	hi	let	red	west	yellow

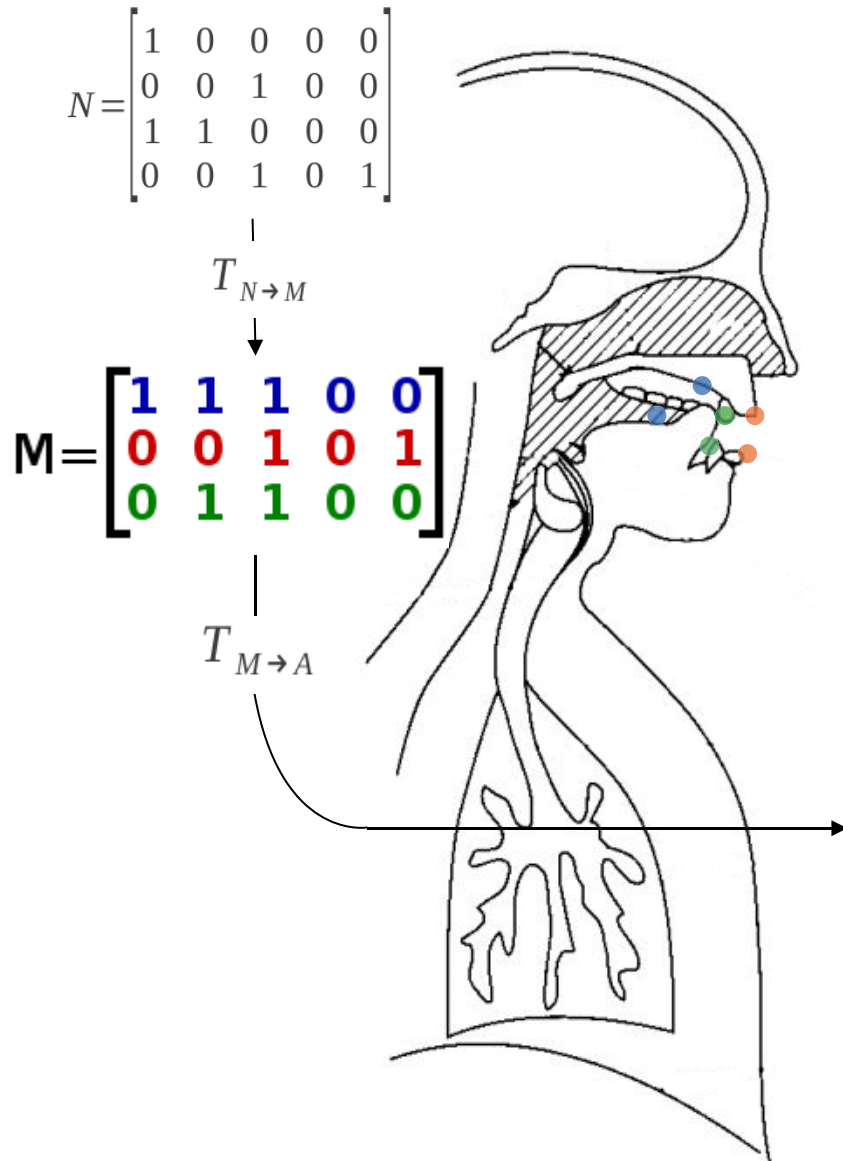
Espacio acústico  
discreto.

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Marcos  
Trevisan  
Florenca  
Assaneo



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## Modelado, control motor y percepción vocal



I:	I	U	u:	Iə	eI		
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Gabriel Mindlin

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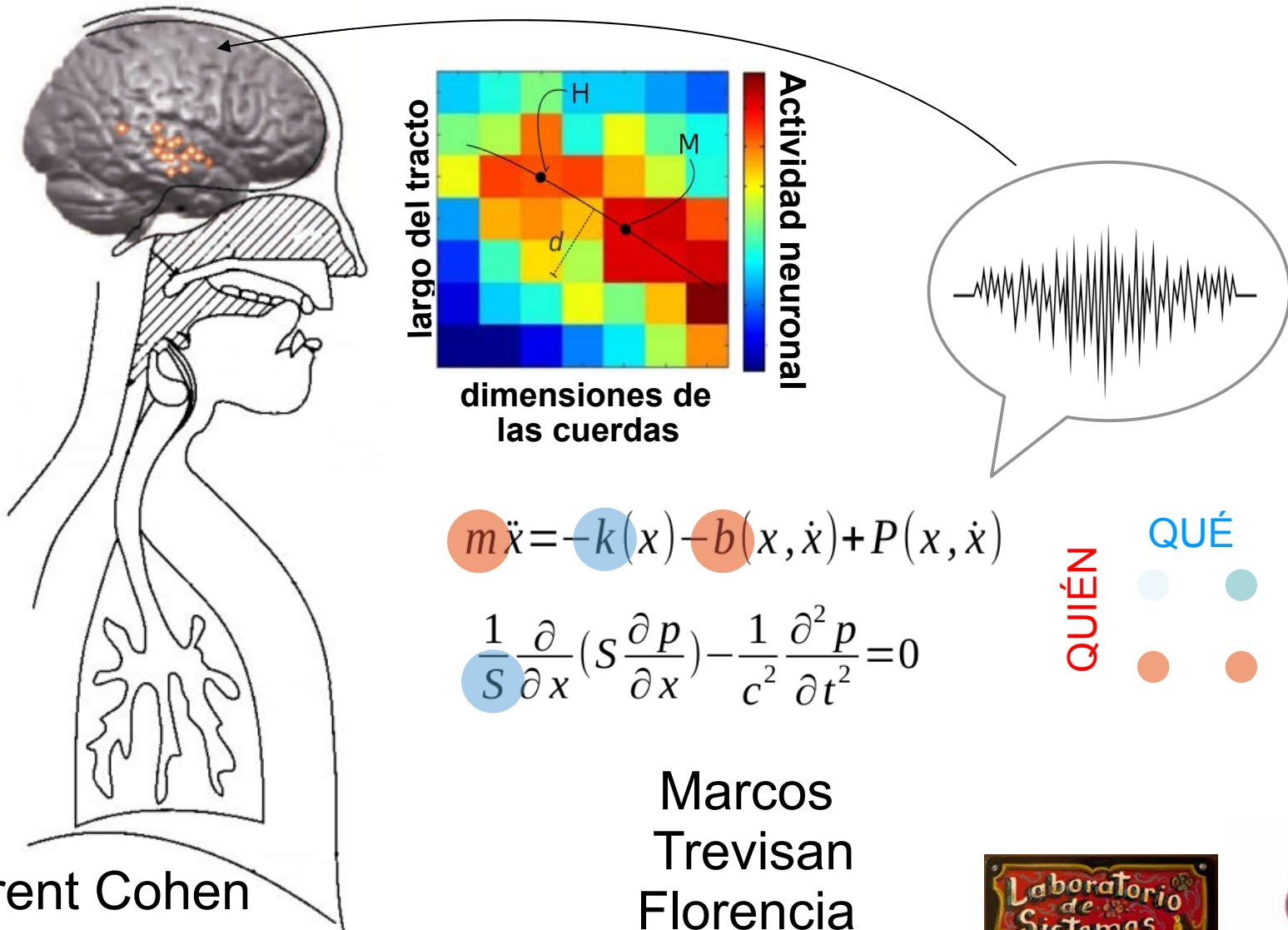
Florencia

Assaneo



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## Modelado, control motor y percepción vocal



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## ¡Gracias por su atención!

